



Backgrounds

Related works:

- Benign overfitting: Overparameterized models often achieve benign overfitting, interpolating the training data while still generalizing well.
- Double descent phenomenon: The testing error characterizes a U-shaped performance curve in the under-parameterized regime, while it decreases again in the over-parameterized regime.

🔍 Motivation: Despite the extensive literature devoted to understanding the double descent phenomenon, there are still several open problems:

- 1) The lack of a general asymptotic analysis framework for generalized nonlinear regression models.
- 2) Existing asymptotic results often remain as self-consistency equations that are hard to estimate.
- 3) Benign overfitting can be caused by overparameterization, and subsampling may also achieve better performance from a dual view.

Contributions:

- Generalized asymptotic analysis framework for nonlinear regression models.
- Trainable nonlinear regression algorithm based on theoretical findings.
- Interesting byproducts: the use of nonlinear feature mapping to reduce effective dimension and the potential benefits of subsampling for generalization.

Preliminaries

Linear Ridge Regression

$$\arg \min_{\eta \in \mathbb{R}^d} \left\{ \frac{1}{n} \sum_{i=1}^n (\eta^\top x_i - y_i)^2 + \lambda \|\eta\|_2^2 \right\}, \quad \text{with}$$

$$\hat{\eta} = (\hat{\Sigma} + \lambda I)^{-1} \hat{\Sigma} \eta_* + (\hat{\Sigma} + \lambda I)^{-1} \frac{X^\top \varepsilon}{n}$$

where $\hat{\Sigma} = \frac{1}{n} X^\top X \in \mathbb{R}^{d \times d}$ the covariance matrix.

Generalized Nonlinear Regression Model

$$\arg \min_{\theta \in \mathbb{R}^p} \left\{ \frac{1}{n} \|\phi(X)\theta - y\|_2^2 + \lambda \|\theta\|_2^2 \right\}, \quad \text{with}$$

$$\hat{\theta} = (\hat{\Sigma}_\phi + \lambda I)^{-1} \hat{\Sigma}_\phi \theta_* + (\hat{\Sigma}_\phi + \lambda I)^{-1} \frac{\phi(X)^\top \varepsilon}{n},$$

where $\phi: \mathbb{R}^d \rightarrow \mathbb{R}^p$ is the feature mapping.

Nonlinear Regression Model with Subsampling

$$\arg \min_{\theta \in \mathbb{R}^p} \left\{ \frac{1}{m} \|S\phi(X)\theta - Sy\|_2^2 + \lambda \|\theta\|_2^2 \right\}, \quad \text{with}$$

$$\hat{\theta} = (\hat{\Sigma}_{S\phi} + \lambda I)^{-1} \hat{\Sigma}_{S\phi} \theta_* + (\hat{\Sigma}_{S\phi} + \lambda I)^{-1} \frac{\phi(X)^\top S^\top S \varepsilon}{m},$$

Assumptions

Assumption 1 (Existence of θ_* in the feature space).

Assumption 2 (Continuous and bounded feature mapping).

Assumption 3 (Covariance condition for nonlinear feature mapping). Suppose Σ_ϕ is invertible and bounded, and the eigenvalues of Σ_ϕ are positive and bounded. $\phi(X) = Z\Sigma_\phi^{1/2}$ where Z has i.i.d. entries with zero mean, and unit variance.

Assumption 4 (Orthogonal subsampling matrix). Suppose the rows of subsampling matrix is orthogonal, such that $SS^\top = I_m$. Meanwhile, $S^\top S$ converges to a deterministic matrix Σ_S .

Assumption 5 (Covariance condition for subsampled nonlinear models). The empirical covariance matrix of $\hat{\Sigma}_{S\phi} = \frac{1}{m} \phi(X)^\top S^\top S \phi(X)$ converges to a deterministic covariance matrix $\Sigma_{S\phi} = \Sigma_\phi^{1/2} Z^\top \Sigma_S Z \Sigma_\phi^{1/2}$. The spectral distribution $F_{\Sigma_{S\phi}}$ of $\Sigma_{S\phi}$ converges to a limit probability distribution μ supported on $[0, +\infty)$ and Σ is invertible and bounded in operator norm.

Asymptotics Results

Theorem 1 (Asymptotic risk for ridge regression). Under Assumptions 2 - 5, the nonlinear ridge regression with subsampling estimator in (??) admits the following limiting variance and bias:

$$\mathbb{E}_\varepsilon \left[\left\| \hat{\theta} - \mathbb{E}_\varepsilon(\hat{\theta}) \right\|_{\Sigma_{S\phi}}^2 \right] \sim \sigma^2 \frac{\text{df}_2(\kappa)}{m - \text{df}_2(\kappa)},$$

$$\left\| \mathbb{E}_\varepsilon(\hat{\theta}) - \theta_* \right\|_{\Sigma_{S\phi}}^2 \sim \frac{m\kappa^2 \theta_*^\top (\Sigma_{S\phi} + \kappa I)^{-2} \Sigma_{S\phi} \theta_*}{m - \text{df}_2(\kappa)}.$$

Corollary 1 (Under-parameterized regime). Under Assumptions 2 - 5, if $\lambda = 0$ and $\gamma < 1$, the nonlinear ridgeless regression with subsampling estimator admits:

$$\mathbb{E}_\varepsilon \left[\left\| \hat{\theta} - \mathbb{E}_\varepsilon(\hat{\theta}) \right\|_{\Sigma_{S\phi}}^2 \right] \sim \sigma^2 \frac{p}{m-p}, \quad \left\| \mathbb{E}_\varepsilon(\hat{\theta}) - \theta_* \right\|_{\Sigma_{S\phi}}^2 = 0.$$

Corollary 2 (Over-parameterized regime). Under Assumptions 2 - 5, if $\lambda = 0$ and $\gamma > 1$, with κ_0 defined by $\text{df}_1(\kappa_0) = m$ the nonlinear ridgeless regression with subsampling estimator admits:

$$\mathbb{E}_\varepsilon \left[\left\| \hat{\theta} - \mathbb{E}_\varepsilon(\hat{\theta}) \right\|_{\Sigma_{S\phi}}^2 \right] \sim \sigma^2 \frac{\text{df}_2(\kappa_0)}{m - \text{df}_2(\kappa_0)},$$

$$\left\| \mathbb{E}_\varepsilon(\hat{\theta}) - \theta_* \right\|_{\Sigma_{S\phi}}^2 = \frac{m\kappa_0^2 \theta_*^\top (\Sigma_{S\phi} + \kappa_0 I)^{-2} \Sigma_{S\phi} \theta_*}{m - \text{df}_2(\kappa_0)}.$$

Algorithm: RFRed

Based on random Fourier features, we devise Random Feature Regression model with Effective Dimension (RFRed)

$$\phi(x) = \sqrt{\frac{2}{p}} \cos(W^\top x + b),$$

where the frequency matrix $W = [w_1, \dots, w_p] \in \mathbb{R}^{d \times p}$ is trainable and initialized by a Gaussian distribution. The phase vectors $b = [b_1, \dots, b_p] \in \mathbb{R}^p$ are drawn uniformly from $[0, 2\pi]$.

Motivated by the asymptotics results, we devise the following objective and optimize θ and W jointly.

$$\mathcal{L}(\theta; W) = \frac{1}{n} \|S\phi(X)\theta - Sy\|_2^2 + \lambda \|\theta\|_2^2 + \beta \hat{\text{df}}_2(\lambda),$$

Complexity. Using batch stochastic gradient method, we have $\nabla_{\theta} \mathcal{L} = \frac{1}{n} \tilde{X}_b^\top (\tilde{X}_b \theta - \tilde{y}_b)$ where $\{\tilde{X}_b \in \mathbb{R}^{b \times p}, \tilde{y}_b \in \mathbb{R}^b\}$ is a batch of $\{S\phi(X), Sy\}$ with the batch size b . We also use the batch data to approximate $\hat{\text{df}}_2(\lambda)$ where \tilde{X} in (??) is replaced by \tilde{X}_b . The compute of $S\phi(X)$ consumes $\mathcal{O}(mnp + ndp)$. With T iterations, the update of θ takes $\mathcal{O}(pbT)$ time, the update of W consumes $\mathcal{O}(pb^2T)$, and the compute of $\hat{\text{df}}_2(\lambda)$ requires $\mathcal{O}(\frac{p^2 n T}{n\alpha})$.

Experiments

